Mitral valve annuloplasty and papillary muscle relocation oriented by 3-dimensional transesophageal echocardiography for severe functional mitral regurgitation

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Objective: The study of the mitral valve apparatus and its modifications during functional mitral regurgitation (FMR) is better revealed by 3-dimensional (3D) transesophageal echocardiography (TOE). To plan mitral valve repair by annuloplasty and papillary muscle (PPM) relocation, we proposed a valve repair procedure oriented by the new main features obtained by real-time 3D TOE reconstruction of the mitral valve apparatus.

Methods: Since January 2008, 25 patients with severe FMR before mitral valve repair were examined. Mean coaptation depth and mean tenting area were 1.3 ± 0.2 cm and 3.2 ± 0.5 cm², respectively. Intraoperative 2D and 3D TOE were performed, followed by a 3D offline reconstruction of the mitral valve apparatus. A schematic mitral valve apparatus model was obtained. A geometric model like a truncated cone was traced in accordance to the preoperative measurements. The size of the prosthetic ring was selected preoperatively according to the anterior leaflet surface. The expected truncated cone after annuloplasty was retraced. A conventional normal coaptation depth about 0.6 cm was used to detect the new position of the PPM tips.

Results: Offline reconstruction of the mitral valve apparatus and respective truncated cone were feasible in all patients. The expected position of the PPM tips desirable to reach a normal tenting area with a coaptation depth 0.6 cm or less was obtained in all patients. After surgery, all parameters were calculated and no statistically significant difference was found compared with the expected data.

Conclusions: PPM relocation plus ring annuloplasty reduce mitral valve tenting and may improve mitral valve repair results for patients with severe FMR. This technique may be easily and precisely guided by preoperative offline 3D echocardiographic mitral valve reconstruction. (J Thorac Cardiovasc Surg 2012;143:S38-42)

Functional mitral regurgitation (FMR) remains one of the most complex and unresolved aspects in the management of heart valve disease. Undersizing mitral valve annuloplasty with a prosthetic ring was first introduced by Bolling and associates¹ and has recently become the preferred treatment for FMR. However, in several series this therapeutic approach has been associated with recurrence of mitral regurgitation (MR) in as much as 30% of patients at 6 months

and 60% of patients 3 to 5 years after surgery.^{2,3} The underlying myocardial pathology in FMR may be ischemic or idiopathic. However, in both cases left ventricular (LV) remodeling leads to mitral valve annulus dilatation, flatness, papillary muscle (PPM) displacement, and mitral leaflet tethering. The pathologic 3-dimensional (3D) anatomy of FMR is complex and varies extensively between patients. The inconsistent clinical response to annuloplasty strongly suggests that there is significant variability in the main contributors to mitral valve incompetence in individual cases. The ability to determine the relative contribution of annular dilatation and leaflet tethering on FMR could help in making clinical decisions in favor of either isolated annuloplasty or more complex surgery combining repair and a subvalvular approach like PPM relocation.⁴ Displacement of the PPMs owing to LV remodeling is a key feature in the development of FMR. Therefore, a detailed preoperative 3D analysis of the entire mitral valve apparatus (MVA) is mandatory for planning surgical strategy.⁵ Real-time 3D echocardiography allows accurate evaluation of the MVA, including the LV chamber and PPM position.⁶ Recent development of matrix-array transducers has made real-time 3D echocardiography a clinically applicable tool and has affected mitral valve repair strategies.⁷ We postulated that in

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Abbreviations and Acronyms

- 2D = 2-dimensional
- 3D = 3-dimensional
- FMR = functional mitral regurgitation
- LV = left ventricle (ventricular)
- MR = mitral regurgitation
- MVA = mitral valve apparatus
- PPM = papillary muscle
- PTFE = polytetrafluoroethylene
- TOE = transesophageal echocardiography

selected patients with FMR a more comprehensive assessment of the 3D anatomy of the MVA using a dedicated mitral valve quantification software (QLab-MVQ; Philips Medical Systems, Andover, Mass) would represent an initial step toward a patient-specific repair approach. In the present study, we performed a mitral valve annuloplasty plus PPM relocation oriented by preoperative real-time 3D echocardiography.

METHODS

Population

Since January 2008, a total of 25 patients (mean age, 63 ± 5 years) with FMR were scheduled in our institution for mitral valve repair with or without coronary artery bypass grafting. There were 15 patients with ischemic and 10 with idiopathic cardiomyopathy. All patients were in a New York Heart Association functional class of more than II. Mean LV ejection fraction was 34% ± 8%. All patients had mitral annulus dilatation and symmetric leaflet tethering owing to PPM displacement (MR type I + IIIb of Carpentier’s classification). Mean coaptation depth and mean tenting area were 1.3 ±

0.2 cm and 3.2 ± 0.5 cm², respectively. Intraoperative 2-dimensional (2D) and real-time 3D transesophageal echocardiography (TOE) were performed, followed by an offline reconstruction of the MVA using QLab-MVQ software and QLab-3DQ advanced software (Philips Medical Systems).

Real-Time 3D TOE Data Acquisition and Analysis

TOE was performed using the iE33 ultrasound imaging system (Philips Medical Systems) equipped with the fully sampled matrix-array TOE transducer (X7-2t). The probe was positioned at the midesophageal level at a 0° tilt (4-chamber view). Electrocardiographically gated full-volume images were acquired during 6 consecutive cardiac cycles. Care was taken to include the entire MVA throughout the acquisition. The images were acquired during a brief suspension of mechanical ventilation to avoid stitch artifacts, and special care was taken to stabilize the probe during data acquisition. All images were digitally stored for offline analysis with the MVQ software. This software helps to build a 3D model, step by step, of the MVA (annulus, anterior and posterior leaflets, coaptation line, and potential coaptation defects, as well as the angles between the mitral leaflets and the plane of the annulus). Moreover, the position of the PPMs was also evaluated.

MVA Analysis With MVQ Software

Off-line preoperative construction of the MVA. The measurements of the MVA included the intercommissural and anteroposterior annular diameters, the area of the anterior and posterior leaflets, the tenting area and volume, the coaptation depth, the angles between the mitral annulus and the mitral leaflets, and the distance between the interpapillary muscles. The interpapillary distance was measured between PPM tips; the distance between each papillary muscle tip and its ipsilateral and contralateral annulus was also calculated on multislice images view (Figure 1, A). The shape of the mitral valve annulus and the coaptation line between the leaflets were traced to have a schematic model of the mitral valve annulus and leaflets (Figure 1, B). A schematic model of the mitral valve apparatus was obtained by QLab-MVQ (Figure 2). A baseline truncated cone was constructed in all patients according to the preoperative anteroposterior and intercommissural annulus diameters, the distance between the

FIGURE 1. A, Mitral valve annulus diameters and distance between the tip of PPM and the ipsilateral annulus were measured on multislice systodiastolic views of the mitral valve apparatus and offline reconstruction by MVQ software. B, The shape of the annulus and leaflets was traced. AL, Anterolateral; PM, posteromedial; Ao, aorta; SL, septolateral; AML, anterior mitral leaflet; PML, posterior mitral leaflet; APM, anterior papillary muscle; PPM, posterior papillary muscle.

FIGURE 2. Schematic mitral valve apparatus model and the respective truncated cone were traced. AL, Anterolateral; PM, posteromedial; Ao, aorta; 3D, 3-dimensional.

tips of PPMs, and the distance between the tips of each PPM and the ipsilateral annulus.

Preoperative offline reconstruction of the expected MVA after annuloplasty. The prosthetic ring was selected according to the surface area of the anterior mitral leaflet measured preoperatively using the MVQ software (*green zone*). The free edge of the leaflet (*red zone*) was excluded because it represents the coaptation surface (Figure 3). A new expected truncated cone structure was traced considering the diameters of the selected prosthetic ring instead of the native valve annulus diameter (Figure 4). An expected new tenting area and coaptation depth (expected after annuloplasty) were obtained. Moreover, a normal coaptation depth (about 0.6 cm) was considered as reference and traced into the new truncated cone. First we put into the new tenting area the length of the new

desirable coaptation depth and then we drew 2 new diagonals (Figure 4). Thus, we calculated the new position of the PPM head that might be reached by relocation of the PPMs to reduce the tenting area and obtain a desirable coaptation depth. We measured the distance between the new position of the PPM tips and the previous position. This distance was equal to the amount of PPM relocation of each muscle. Finally, the distance between the plane of the annulus and the new position of each PPM head was calculated preoperatively and used during surgery as a reference to check the correct position of the PPMs after relocation. After surgery, all parameters were measured, recalculated, and compared with expected data (Figure 5).

Surgical Technique

The PPM relocation was performed using polytetrafluoroethylene (PTFE) CV-4 suture (Gore-Tex; W. L. Gore & Associates, Inc, Flagstaff, Ariz) to reduce tenting area and coaptation depth. PPM relocation was performed by passing a PTFE suture through the fibrous portion of each PPM head reinforced by pledgets. Each needle of the double-armed suture was then passed up through the ipsilateral mitral annulus just between the fibrous trigone and the commissure. Two among the 3 heads (anterior and medial) of the posterior PPM were relocated by a couple of PTFE sutures. Mitral annuloplasty was then performed in all patients using a complete Edward Physio II annuloplasty ring (Edwards Lifesciences, Irvine, Calif) or a saddle rigid ring (St Jude Medical, Inc, St Paul, Minn). The size of the ring was selected preoperatively (based on its surface area given by the manufacturer) according to the surface area of the anterior mitral leaflet measured using MVQ. Interrupted 2-0 Ti-Cron U stitches (Ethicon, Inc, Somerville, NJ) were placed through the annulus and the prosthetic ring was seated. The PTFE sutures placed previously to the tips of both PPMs and subsequently through the mitral annulus were sutured to the ring and pulled up, drawing the PPMs tips closer to the annulus. The final position of both PPM tips (according to the distance measured and expected preoperatively using offline reconstruction) were estimated by measuring the length of the PTFE stitch from the PPM tips to the annulus. Finally, the sutures were tied. The adequacy of repair was tested using a saline solution to feel the LV.

FIGURE 3. Surface of the leaflets and angle between the leaflets and the mitral annulus were calculated. AL, Anterolateral; PM, posteromedial; Ao, aorta.

FIGURE 4. Expected truncated cone was retraced according to the diameters of the selected ring despite the normal annular diameter; expected normal coaptation depth was used to obtain the expected position of the papillary muscle (PPM) tips.

RESULTS

All patients had suitable real-time 3D TOE images for offline quantification of the MVA. The surface area of the anterior leaflet was obtainable in all patients. The mean time duration for image acquisition and offline reconstruction lasted 12 ± 5 minutes. No in-hospital death occurred. Four patients had trivial to mild residual MR postoperatively and a mean follow-up of 14 ± 4 months. The schematic reconstruction of the MVA using the QLab-MVQ software allowed the reconstruction of the truncated cone in all patients. After selection of the prosthetic ring size, the expected truncated cone geometry

was obtained and the new position of PPM tips was detected. All expected diameters and distances of the MVA were measured and compared with postoperative data. No statistically significant difference was found between expected and postoperative intercommissural ($P = .35$) and septolateral ($P = .89$) annular diameters, coaptation depth ($P = .78$), and the distances between the anterior ($P = .23$) and posterior ($P = .34$) PPM tip and ipsilateral annulus. All data are listed in Table 1.

COMMENTS

The optimal surgical treatment for FMR remains controversial. FMR is determined by complex mechanisms. LV remodeling with PPM displacement and leaflet tethering, reduced systolic leaflet closing force, dyssynchrony, and mitral annular enlargement are all contributors to FMR.⁷ Restrictive annuloplasty is the most commonly performed surgical procedure for FMR and provides good results in selected patients with minimal LV dilatation and mitral valve deformation. However, the persistence and recurrence of FMR in patients who had undergone restrictive annuloplasty remains high (up to 30% at 6 months postoperatively). Some authors have found that at 10-year follow-up persistent FMR can attenuate the potential survival benefit of a combined procedure compared with coronary artery bypass grafting alone (10-year survival for both being approximately 50%).⁸ The relatively high recurrence rate of FMR after restrictive annuloplasty has led to the development of new alternative surgical procedures targeting the subvalvular apparatus and the LV. The objective is to tailor the ideal combination of annular, valvular, chordal,

FIGURE 5. Postrepair parameter measurements. AL, Anterolateral; PM, posteromedial; Ao, aorta; A, anterior; P, posterior.

TABLE 1. Three-dimensional echocardiographic data: Before and after mitral valve surgery

IMR 3D variables	Baseline data	MVQ offline analysis expected		P value*
		after annuloplasty	Postoperative data	
Mitral annulus				
Intercommissural distance	51.8 ± 1.2	29 ± 7	30 ± 3	.35
Septolateral distance	44.8 ± 0.7	21 ± 8	21 ± 2	.89
Mitral leaflets				
Anterior leaflet area (mm ²)	722.6 ± 256.2	411 ± 61	395 ± 56	.52
Subvalvular distance (mm)				
AL. PPM–ipsilateral annulus	48 ± 5	34 ± 5	35 ± 3	.23
PM. PPM–ipsilateral annulus	41 ± 3	31 ± 4	30 ± 2	.34
PPM tips*	25 ± 0.2	20 ± 3	19 ± 1.5	.42
Leaflet angles				
Posterior leaflet angle (°)	45.8 ± 4.2	37.2 ± 5.2	38.5 ± 3.2	.12
Anterior leaflet angle (°)	37.5 ± 2.8	33.2 ± 3.1	31.2 ± 2.8	.08
Coaptation				
Coaptation depth (cm)	1.3 ± 0.2	0.6 ± 0.2	0.55 ± 0.2	.78
Tethering				
Tenting area (cm ²)	3.2 ± 0.5	—	1.2 ± 0.2	—
Tenting volume (mL)	8.9 ± 1.7	—	1.4 ± 0.3	—

IMR, Ischemic mitral regurgitation; AL, anterolateral; PM, posteromedian; PPM, papillary muscle. *Significance between expected and postoperative data.

PPM, and ventricular relationships on the basis of preoperative clinical and echocardiographic characteristics to achieve the best repair result in each patient.⁹ This will lead to a “continuum of therapies” that can be customized to the individual patient’s needs. In the present study, we have reported, for the first time, an initial step toward a patient-specific therapeutic approach to FMR using preoperative 3D reconstruction of the MVA complex with the MVQ software. The complex 3D relationship between the PPMs and the mitral annulus was revealed as a truncated cone. After adjustment to the measured preoperative ring size and referring to a normal coaptation depth, the new positions of the PPM heads were obtained and taken into account for the surgical intervention. After PPM repositioning, this complex 3D PPM–annulus geometric shape was retraced; it mimics the preoperative retraced one as a whole. Our data highlighted that PPM relocation and mitral valve annuloplasty could be oriented by preoperative 3D echocardiography and offline analysis using the MVQ software. Furthermore, with increased clinical experience, this approach might adequately predict the surgical gestures.

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